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# **Notes:**

# 80286 Microprocessor

The 80286 microprocessor subsystem has the following:

- 24-bit address
- 16-bit data interface
- Extensive instruction set, including string I/O
- Hardware fixed-point multiply and divide
- · Two operational modes:
  - 8086-compatible Real Address
  - Protected Virtual Address.
- 16MB (MB equals 1,048,576 or 2<sup>20</sup> bytes) of physical address space
- 1GB (GB equals 1,073,741,824 or 2<sup>30</sup> bytes) of virtual address space.

### **Real-Address Mode**

In the real-address mode, the address space of the system microprocessor is a contiguous array of up to 1MB. The system microprocessor generates 20-bit physical addresses to address memory.

The segment portion of the pointer is interpreted as the upper 16 bits of a 20-bit segment address; the lower 4 bits are always 0. Therefore, segment addresses begin on multiples of 16 bytes.

All segments in the real-address mode are 64KB (KB equals 1024 bytes) and can be read, written, or executed. An exception or interrupt can occur if data operands or instructions attempt to wrap around the end of a segment (for example, a word with its low-order byte at offset hex FFFF and its high-order byte at hex 0000). If, in the real-address mode, the information contained in the segment does not use the full 64KB, the unused end of the segment can be overlaid by another segment to reduce physical memory requirements.

### **Protected Virtual Address Mode**

The protected virtual address mode (hereafter called protected mode) offers extended physical and virtual memory address space, memory protection mechanisms, and new operations to support operating systems and virtual memory.

The protected mode provides a virtual address space of 1GB for each task mapped into a 16MB physical address space. The virtual

address space may be larger than the physical address space, because any use of an address that does not map to a physical memory location will cause a restartable exception.

Like the real-address mode, the protected mode uses 32-bit pointers, consisting of 16-bit selector and offset components. The selector specifies an index into a memory-resident table rather than the upper 16 bits of a real address. The 24-bit base address of the desired segment is obtained from a table in memory. The 16-bit offset is added to the segment base address to form the physical address. The system microprocessor automatically refers to the tables whenever a segment register is loaded with a selector. All instructions that load a segment register refer to the table without additional program support. Each entry in a table is 8-bytes wide.

# 80287 Math Coprocessor

The optional 80287 Math Coprocessor enables the system to perform high-speed arithmetic, logarithmic, and trigonometric operations. The coprocessor works in parallel with the microprocessor. The parallel operation decreases operating time by allowing the coprocessor to do mathematical calculations while the microprocessor continues to do other functions.

The coprocessor works with seven numeric data types, which are divided into the following three classes:

- Binary integers (three types)
- Decimal integers (one type)
- Real numbers (three types).

# Programming Interface

The coprocessor offers extended data types, registers, and instructions to the microprocessor. The coprocessor has eight 80-bit registers, which provide the equivalent capacity of forty 16-bit registers. This register space allows constants and temporary results to be held in registers during calculations, thus reducing memory access, improving speed, and increasing bus availability. The register space can be used as a stack or as a fixed register set. When used as a stack, only the top two stack elements are operated on.

The following figure shows representations of large and small numbers in each data type.

Data Type	Bits	Significant Digits (Decimal)	Approximate Range (Decimal)
Word Integer	16	4	$-32,768 \le x \le +32,767$
Short Integer	32	9	$-2 \times 10^9 \le x \le +2 \times 10^9$
Long Integer	64	19	$-9 \times 10^{18} \le x \le +9 \times 10^{18}$
Packed Decimal	80	18	$-999 \le x \le +999$ (18 digits)
Short Real *	32	6 - 7	$8.43 \times 10^{-37} \le x \le 3.37 \times 10^{38}$
Long Real *	64	15 - 16	$4.19 \times 10^{-307} \le x \le 1.67 \times 10^{308}$
Temporary Real **	80	19	$3.4 \times 10^{-4932} \le x \le 1.2 \times 10^{4932}$

<sup>\*</sup> The short-real and long-real data types correspond to the single-precision and double-precision data types.

Figure 1. 80287 Data Types

### Hardware Interface

The coprocessor uses the same clock generator as the microprocessor and operates in the asynchronous mode. The coprocessor is wired so that it functions as an I/O device through I/O port addresses hex 00F8, 00FA, and 00FC. The microprocessor sends opcodes and operands through these I/O ports. It also receives and stores results through the same I/O ports. The coprocessor 'busy' signal informs the microprocessor that it is executing; the microprocessor Wait instruction forces the microprocessor to wait until the coprocessor is finished executing.

The coprocessor detects six different exception conditions that can occur during instruction execution:

- Invalid operation
- Denormal operand
- Zero-divide
- Overflow
- Underflow
- Precision.

<sup>\*\*</sup> The temporary-real data type corresponds to the extended-precision data Type.

If the appropriate exception-mask bit within the coprocessor is not set, the coprocessor activates the 'error' signal. The 'error' signal generates a hardware interrupt (IRQ 13) causing the 'busy' signal to be held in the busy state. The 'busy' signal may be cleared by an 8-bit I/O Write command to address hex 00F0, with D7 through D0 equal to 0. This action also clears IRQ 13.

The power-on self-test code in the system ROM enables IRQ 13 and sets up its vector to point to a routine in ROM. The ROM routine clears the 'busy' signal latch and then transfers control to the address pointed to by the nonmaskable interrupt (NMI) vector. This maintains code compatibility across the IBM Personal Computer and Personal System/2 product lines. The NMI handler reads the coprocessor status to determine if the coprocessor generated the NMI. If it was not generated by the coprocessor, control is passed to the original NMI handler.

The coprocessor has two operating modes: real-address mode and protected mode. They are similar to the two modes of the microprocessor. The coprocessor is in the real-address mode if reset by a power-on reset, system reset, or I/O write operation to port hex 00F1. This mode is compatible with the 8087 Math Coprocessor used in IBM Personal Computers. The coprocessor is placed in the protected mode by executing the SETPM ESC instruction. It is placed back in the real-address mode by an I/O write operation to port hex 00F1, with D7 through D0 equal to 0.

Detailed information for the internal functions of the 80287 Math Coprocessor is in the books listed in the Bibliography. Also see "Compatibility" for more information.

# 80386 Microprocessor

The 80386 microprocessor subsystem has the following:

- 32-bit address
- 32-bit data interface
- Extensive instruction set, including string I/O
- · Hardware fixed-point multiply and divide
- · Three operational modes:
  - Real Address
  - Protected Virtual Address
  - Virtual 8086.

- 4GB of physical address space
- 8 general-purpose 32-bit registers
- 64TB (TB equals 1,099,511,627,776 or 240 bytes) of total virtual-address space.

#### Real Address Mode

In the real-address mode, the address space of the system microprocessor is a contiguous array of up to 1MB. The system microprocessor generates 20-bit physical addresses to address memory.

The segment portion of the pointer is interpreted as the upper 16 bits of a 20-bit segment address; the lower 4 bits are always 0. Therefore, segment addresses begin on multiples of 16 bytes.

All segments in the real-address mode are 64KB and can be read. written, or executed. An exception or interrupt can occur if data operands or instructions attempt to wrap around the end of a segment (for example, a word with its low-order byte at offset hex FFFF and its high-order byte at hex 0000). If, in the real-address mode, the information contained in the segment does not use the full 64KB, the unused end of the segment can be overlaid by another segment to reduce physical memory requirements.

#### **Protected Virtual Address Mode**

The protected virtual-address mode offers extended physical and virtual memory address space, memory protection mechanisms, and new operations to support operating systems and virtual memory.

The protected mode provides up to 64TB of virtual address space for each task mapped into a 4GB physical address space.

From a programmer's point of view, the main difference between the real-address mode and protected mode is the increased address space and the method of calculating the base address. The protected mode uses 32- or 48-bit pointers, consisting of 16-bit selector and 16or 32-bit offset components. The selector specifies an index into one of two memory-resident tables, the global descriptor table (GDT) or the local descriptor table (LDT). These tables contain the 32-bit base address of a given segment. The 32-bit effective offset is added to the segment base address to form the physical address. The system microprocessor automatically refers to the tables whenever a segment register is loaded with a selector. All instructions that load

a segment register refer to the memory-resident tables without additional program support. The memory-resident tables contain 8-byte values called descriptors.

The paging option provides an additional way of managing memory in the very large segments of the 80386. Paging operates in the protected mode only, beneath segmentation. The paging mechanism translates the protected linear address (which comes from the segmentation unit) into a physical address. When paging is not enabled, the physical address is the same as the linear address. The following figure shows the 80386 addressing mechanism.

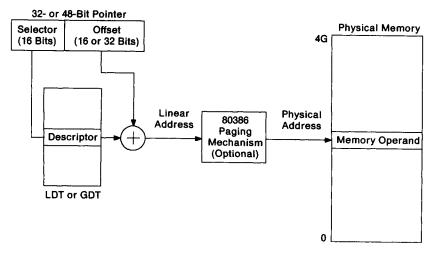


Figure 2. 80386 Addressina

### Virtual 8086 Mode

The virtual-8086 mode ensures compatibility of programs written for 8086- and 8088-based systems by establishing a protected 8086 environment within the 80386 multitasking framework.

Since the address space of an 8086 is limited to 1MB, the logical addresses generated by the virtual-8086 mode lie within the first 1MB of the 80386 linear address space. To support multiple virtual-8086 tasks, paging can be used to give each virtual-8086 task a 1MB address space anywhere in the 80386 physical address space.

On a task-by-task basis, the value of the virtual-8086 flag (VM86 flag in the Flags register) determines whether the 80386 behaves as an 80386 or as an 8086. Some instructions, such as Clear Interrupt Flag.

can disrupt all operations in a multitasking environment. The 80386 raises an exception when a virtual-8086 mode task attempts to execute an I/O instruction, interrupt-related instruction, or other sensitive instruction. Anytime an exception or interrupt occurs, the 80386 leaves the virtual 8086 mode, making the full resources of the 80386 available to an interrupt handler or exception handler. These handlers can determine if the source of the exception was a virtual-8086 mode task by inspecting the VM86 flag in the Flags image on the stack. If the source is a virtual-8086 mode task, the handler calls on a routine in the operating system to simulate an 8086 instruction and return to the virtual-8086 mode.

### 80386 Paging Mechanism

The 80386 uses two levels of tables to translate the linear address from the segmentation unit into a physical address. There are three components to the paging mechanism:

- · Page directory
- Page tables
- · Page frame (the page itself).

The figure on the following page shows how the two-level paging mechanism works.

<sup>1</sup> The routine in the operating system, called a virtual machine monitor, simulates a limited number of 8086 instructions.

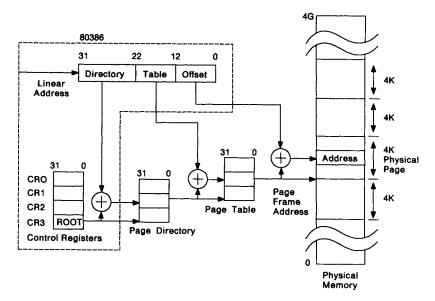


Figure 3. Paging Mechanism

CR2 is the Page-Fault Linear-Address register. It holds the 32-bit linear address that caused the last detected page fault.

CR3 is the Page Directory Physical Base Address register. It contains the physical starting address of the page directory.

The page directory is 4KB and allows up to 1024 page-directory entries. Each page-directory entry contains the address of the next level of tables, the page tables, and information about the page tables. The upper 10 bits of the linear address (A22 through A31) are used as an index to select the correct page-directory entry.

Each page table is 4KB and holds up to 1024 page-table entries. Page-table entries contain the starting address of the page frame and statistical information about the page. Address bits A12 through A21 are used as an index to select one of the 1024 page-table entries. The upper 20 bits of the page-frame address (from the page-table entry) are linked with the lower 12 bits of the linear address to form the physical address. The page-frame address bits become the most-significant bits; the linear-address bits become the least-significant bits.

# 80387 Math Coprocessor

The optional 80387 Math Coprocessor enables the system to perform high-speed arithmetic, logarithmic, and trigonometric operations. The 80387 effectively extends the 80386 register and instruction set for existing data types and also adds several new data types. The following figure shows the four data type classifications and the instructions associated with each.

Classification	Size	Instructions		
Integer	16, 32, 64 Bits	Load, Store, Compare, Add, Subtract, Multiply, Divide		
Packed BCD*	80 Bits	Load, Store		
Real	32, 64 Bits	Load, Store, Compare, Add, Subtract, Multiply, Divide		
Temporary Real	80 Bits	Add, Subtract, Multiply, Divide, Square Root, Scale, Remainder, Integer Part, Change Sign, Absolute Value, Extract Exponent and Significand, Compare, Examine, Test, Exchange Tangent, Arctangent, $2^x-1$ , $Y^*Log_2$ (X+1), $Y^*Log_2$ (X), Load Constant (0.0, $\pi$ , etc.), Sine, Cosine, Unordered Compare		
* BCD = Binary-c	* BCD = Binary-coded decimal			

Figure 4. Data Type Classifications and Instructions

The 80386/80387 configuration fully conforms to the ANSI<sup>2</sup> and IEEE<sup>3</sup> floating-point standard and are upward, object-code compatible from 80286/80287- and 8086/8087-based systems.

<sup>&</sup>lt;sup>2</sup> American National Standards Institute

<sup>3</sup> Institute of Electrical and Electronics Engineers

# 80387 To 80486 Math Coprocessor Compatibility

The 80387 floating-point coprocessor is integrated into the 80486 microprocessor. All numeric 80387 instructions are fully compatible with the 80486 floating-point unit. The 80486 microprocessor supports the 80486 floating-point error reporting modes to ensure DOS compatibility with 80386/80387 systems.

The coprocessor presence test will always show the presence of a coprocessor in the 80486.

Programs for the 80386/80387 systems that explicitly reset the coprocessor by writing to hex 00F1 will no longer function because the coprocessor is an integral part of the microprocessor.

Coprocessor reset or initialization must be accomplished through FINIT/FSAVE.

| For DOS compatibility, the numeric exception bit Control Register 0 | must be set to 0.

# **Programming Interface**

The 80387 is not sensitive to the processing mode of the 80386. The 80387 functions the same whether the 80386 is executing in real-address mode, protected mode, or virtual-8086 mode. All memory access is handled by the 80386; the 80387 merely operates on instructions and values passed to it by the 80386.

All communication between the 80386 and 80387 is transparent to application programs. The 80386 automatically controls the 80387 whenever a numeric instruction is executed. All physical and virtual memory is available for storage of instructions and operands of programs that use the 80387. All memory address modes, including use of displacement, base register, index register, and scaling are available for addressing numeric operands.

The coprocessor has eight 80-bit registers. The total capacity of these eight registers is equivalent to twenty 32-bit registers. This register space allows constants and temporary results to be held in registers during calculations, thus reducing memory access, improving speed, and increasing bus availability. The register space can be used as a stack or as a fixed register set. When it is used as a stack, only the top two stack elements are operated on.

The following figure shows the seven data types supported by the 80387 Math Coprocessor.

Data Type	Range	Precision
Word Integer	104	16 Bits
Short Integer	10 <sup>9</sup>	32 Bits
Long Integer	10 <sup>19</sup>	64 Bits
Packed BCD	10 <sup>18</sup>	18 Digits ( 2 digits per byte)
Single Precision (Short Real)	10 <sup>±38</sup>	24 Bits
Double Precision (Long Real)	10 <sup>±308</sup>	53 Bits
Extended Precision (Temporary Real)	10 <sup>±4932</sup>	64 Bits

Figure 5. 80387 Data Types

## Hardware Interface

The 80387 Math Coprocessor uses the same clock generator as the 80386 system microprocessor. The coprocessor is wired so that it functions as an I/O device through I/O port addresses hex 00F8, 00FA, and 00FC. The system microprocessor sends opcodes and operands through these I/O ports. The coprocessor 'busy' signal informs the system microprocessor that it is executing an instruction; the system microprocessor Wait instruction forces the system microprocessor to wait until the coprocessor is finished executing the instruction.

The coprocessor detects six different exception conditions that can occur during instruction execution:

- Invalid operation
- · Denormal operand
- Zero-divide
- Overflow
- Underflow
- Precision.

If the appropriate exception mask bit within the coprocessor is not set, the coprocessor activates the 'error' signal. The 'error' signal generates a hardware interrupt (IRQ 13) causing the 'busy' signal to be held in the busy state. The 'busy' signal can be cleared by an 8-bit I/O Write command to address hex 00F0, with D7 through D0 equal to 0. This action also clears IRQ 13.

The power-on self-test code in the system ROM enables IRQ 13 and sets up its vector to point to a routine in ROM. The ROM routine clears the 'busy' signal latch and then transfers control to the address pointed to by the (NMI) vector. This maintains code compatibility across the IBM Personal Computer and Personal System/2 product lines. The NMI handler reads the status of the coprocessor to

determine if the coprocessor generated the NMI. If it was not generated by the coprocessor, control is passed to the original NMI handler.

Detailed information about the internal functions of the 80387 Math Coprocessor is in the books listed in the Bibliography. Also see "Compatibility" for more information.

# 80486 Microprocessor

The 80486 microprocessor subsystem has the following:

- 32-bit address
- 32-bit data interface
- Extensive instruction set, including string I/O
- Hardware fixed-point multiply and divide
- Three operational modes:
  - Real Address
  - Protected Virtual Address
  - Virtual 8086
- · 4GB of physical address space
- 8 general-purpose 32-bit registers
- 64TB of total virtual-address space
- Internal 8KB, set-associative cache with controller
- Internal 80387 coprocessor.

The 80486 microprocessor is compatible with the 80386 in the following areas:

- Real Address Mode
- Protected Virtual Address Mode
- Virtual 8086 Mode
- 80386 Paging Mechanism
- All published 80386 instructions
- All published 80387 instructions.

The complete 80387 Math Coprocessor instruction set and register set have been included in the 80486 as a floating-point unit. No I/O cycles are executed during floating-point instructions. The 80486 microprocessor is 80386/80387 compatible except for resets to the floating-point unit. Software must use FINIT/FSAVE to reset the floating-point unit (math coprocessor). The instruction and data pointers are set to zero after FINIT/FSAVE.

### | Cache Control

The 80486 microprocessor contains an 8KB integrated cache for code and data. The cache is managed in two ways, and the operation of the cache has no effect on the operation of any program.

| The cache is managed by bit 30 - Cache Disable (CD) and bit 29 - | Not Write Through (NW) in Control Register 0 (CR0):

Bit 30 CD	Bit 29 NW	Operating Mode
1	1	Cache fills disabled, write-through and invalidate disabled
1	0	Cache fills disabled, write-through and invalidate enabled
0	1	Reserved
0	0	Cache fills enabled, write-through and invalidate enabled (Normal operating mode)

| Figure 6. Control Register 0

# | Cache Paging Control

The page-write-through (PWT) bit and the page-cache-disabled (PCD) bit are two new bits defined in entries in both levels of the page table structure, the page-directory table and the page-table entry, and in Control Register 3.

The PWT bit (bit 4) controls cache write policy. When this bit is set to 1, a write-through policy for the current 4KB page is defined. When this bit is set to 0, it allows the possibility of write-back policy. This bit is ignored internally because the 80486 microprocessor has a write-through-only cache. The PWT bit can be used to control the write policy of a second-level (external) cache.

The PCD bit (bit 3),in conjunction with the KEN# (cache enabled) input signal and the cache-enable and write-transparent bits in Control Register 0 (CR0), controls the ability of cache. When this bit is set to 1, caching is disabled for the 4KB page regardless of the KEN#, cache-enable bit, and write-through bit. These two bits are also driven external to the processor during memory access to manage a second-level cache, if one exists.

The page-write-through and page-cache-disable bits for a bus cycle are obtained either from Control Register 3, the page-directory entry, or the page-table entry, depending on the type of cycle performed.

# Page Protection Feature

The 80486 microprocessor has a new protection feature. The write-protect (WP) bit in CR0 has been added to the 80486 microprocessor to protect read-only pages from supervisor write accesses. The 80386 microprocessor allows a read-only page to be written from protection level 0, 1, or 2. When the WP bit is set to 0, the 80486 microprocessor is in the 80386-compatible mode. When the WP bit is set to 0, the supervisor write access to a read-only page (Read/Write is set to 0) causes a page fault (exception 14).

The write-protect bit has a new feature. This feature involves the use of three new bits in CR0:

- User/Supervisor U/S
- Read/Write R/W
- Write/Protect WP.

The compatible protection feature is described by the following table.

U/S	R/W	WP	User Access	Supervisor Access
0	0	0	None	Read/Write/Execute
0	1	0	None	Read/Write/Execute
1	0	0	Read/Execute	Read/Write/Execute
1	1	0	Read/Write/Execute	Read/Write/Execute

Figure 7. 80386 Compatible Operation

The new protection feature is given by the following table.

U/S	R/W	WP	User Access	Supervisor Access
0	0	1	None	Read/Execute
0	1	1	None Read/Write/Execute	
1	0	1	Read/Execute Read/Execute	
1	1	1	Read/Write/Execute	Read/Write/Execute

| Figure 8. 80486 Protection Operation

# New Alignment Check

| The Flag register in the 80486 microprocessor contains a new bit not | available in the 80386. The new bit, alignment check, is bit 18 of the | Flag register and enables fault reporting on accesses to misaligned | data (through interrupt 17 with an error code 0).

When alignment check is set to 1, it enables fault reporting if memory reference is to a misaligned address. A misaligned address is a word access to an odd address, a doubleword access to an address not on a doubleword boundary, or an 8-byte reference to an address that is not on a 64-bit boundary.

| Alignment faults are generated only by a program running at | privilege level 3. The alignment-check bit is ignored at privilege | levels 0, 1, and 2.

The alignment-check bit is conditioned by a new alignment mask bit, defined as bit 18 in Control Register 0. The alignment-mask bit controls whether the alignment-check bit in the Flag register can allow an alignment fault. When the alignment-mask bit is set to 0, the alignment-check bit is disabled and compatible with the 80386 microprocessor. When the alignment-mask bit is set to 1, the alignment-check bit is enabled.

### I New Instructions

In addition, the 80486 has six unique instructions that control cache operation:

- Byte Swap (BSWAP)
- Compare and Exchange (CMPXCHG)
- Exchange-and-Add (XADD)
- Invalidate Data Cache (INVD)
- Invalidate TLBN Entry (INVLPG).
- Write-Back and Invalidate Data Cache (WBINVD).

# **80286 Microprocessor Instruction Set**

### **Data Transfer**

MOV = Move

### Register to Register/Memory

1000100w	mod reg r/m

### Register/Memory to Register

1000101w	mod reg r/m
1000101#	mod reg min

### Immediate to Register/Memory

1100011w	mod 0 0 0 r/m	data	data if w = 1
			i I

### Immediate to Register

1 0 1 1 wreg	data	data if w = 1

### Memory to Accumulator

1010000 addr-low addr-high	1010000w	addr-low	addr-high
----------------------------	----------	----------	-----------

#### **Accumulator to Memory**

1010001w	addr-low	addr-high
10100011	addi-10W	aggi-nign

## Register/Memory to Segment Register

10001110	mod 0 reg r/m

#### Segment Register to Register/Memory

10001100	mod 0 re	a r/m

### PUSH - Push

### Memory

	[
	mod 1 1 0 r/w
1111111	i mooriiilr/w
	11100 1 1 0 17 11

### Register

0 1 0 1 0 reg

### Segment Register

000 reg 110

#### **Immediate**

011010s0	data	data if s = 0

## PUSHA = Push All

01100000

### POP - Pop

### Register/Memory

10001111	mod 0 0 0 r/m

### Register

0 1 0 1 1 reg

### Segment Register

			$\neg$
000	reg 1 1 1	reg ≠ 0 1	

# POPA = Pop Ail

01100001

# XCHG = Exchange

Register/Memory with Register

1000011w	mod reg r/m

Register with Accumulator

10010 reg

## IN = Input From

Fixed Port

1110010w	port
	, F

Variable Port

1110110w

## OUT = Output To

**Fixed Port** 

1110011w	port
	P

Variable Port

1110111w

# XLAT = Translate Byte to AL

11010111

# LEA = Load EA to Register

10001101	mod reg r/m

### LDS = Load Pointer to DS

11000101	mod reg r/m	mod ≠ 1 1
----------	-------------	-----------

### LES = Load Pointer to ES

11000100	mod reg r/m mod ≠ 11	

# LAHF - Load AH with Flags

10011111

## SAHF = Store AH with Flags

10011110

# PUSHF = Push Flags

10011100

## POPF = Pop Flags

10011101

## **Arithmetic**

### ADD = Add

### Register/Memory with Register to Either

I	000000dw	mod reg r/m

### Immediate to Register/Memory

		<del></del>	
100000s	w mod 0	00 r/m data	data if sw = 0 1

### Immediate to Accumulator

0000010w	data	data if w = 1
0000010#	Gala	data ii w — 1

## ADC = Add with Carry

#### Register/Memory with Register to Either

000100dw	mod reg r/m

### Immediate to Register/Memory

100000sw	mod 0 1 0 r/m	data	data if sw = 01
1000003#	11100 0 1 0 17111	uata	data ii Sw - 0 i

#### Immediate to Accumulator

0001010w	data	data if w = 1
----------	------	---------------

### INC = Increment

#### Register/Memory

1111111w	mod 0 0 0 r/m
----------	---------------

#### Register

0 1 0 0 0 reg

## SUB = Subtract

## Register/Memory with Register to Either

001010dw	mod reg r/m

# Immediate from Register/Memory

100000sw	mod 1 0 1 r/m	data	data if sw = 01

### Immediate from Accumulator

## SBB = Subtract with Borrow

# Register/Memory with Register to Either

000110dw	mod reg r/m

### Immediate from Register/Memory

100000sw mod 011r/m	data	data if sw = 01
---------------------	------	-----------------

### Immediate from Accumulator

0001110w d	ata	data if w = 1
------------	-----	---------------

### **DEC** = Decrement

#### Register/Memory

1111111w	mod 0 0 1 r/m

#### Register

0 1 0 0 1 reg

### CMP - Compare

### Register/Memory with Register

0011101w	mod reg r/m

#### Register with Register/Memory

0011100w	mod reg r/m

### Immediate with Register/Memory

4000000			1	T	٦
	100000sw	mod 1 1 1 r/m	data	data if sw = 01	1

#### Immediate with Accumulator

0011110w data data if w =	1

### NEG = Change Sign

	<del></del>
1111011w	mod 0 1 1 r/m
1	

## AAA - ASCII Adjust for Add

00110111

### DAA = Decimal Adjust for Add

00100111

### AAS = ASCII Adjust for Subtract

00111111

## DAS = Decimal Adjust for Subtract

00101111

# MUL = Multiply (Unsigned)

1111011w	mod 1 0 0 r/m

# IMUL = Integer Multiply (Signed)

1111011w	mod 1 0 1 r/m
	11100 1 0 1 17111

# IIMUL = Integer immediate Multiply (Signed)

		T	
011010s1	mod reg r/m	data	data if s = 0
		_ uuu	uata ii s - v

# DIV = Divide (Unsigned)

1111011w	mod 1 1 0 r/m
	11104 1 1 0 1/111

# IDIV = Integer Divide (Signed)

1111011w	mod 1 1 1 r/m

# AAM = ASCII Adjust for Multiply

11010100	00001010

# AAD = ASCII Adjust for Divide

11010101	00001010

# **CBW** = Convert Byte to Word

10011000

# CWD = Convert Word to Doubleword

10011001

# Logic

### **Shift/Rotate Instructions**

### Register/Memory by 1

l 1101000w	mod T T T r/m
1 1101000W	: IIIOU 1 1 1 1/111

### Register/Memory by CL

1101001w	mod T T T r/m

### Register/Memory by Count

1100000 w   modifier/m   count	1100000w	mod T T T r/m	count
--------------------------------	----------	---------------	-------

TTT	Instruction	
000	ROL	
001	ROR	
010	RCL	
011	RCR	
100	SHL/SAL	
101	SHR	
111	SAR	

### AND = And

### Register/Memory and Register to Either

001000dw	mod reg r/m

### Immediate to Register/Memory

1 0 0 0 0 0 0 w mod 100 r/m data	data if w = 1
----------------------------------	---------------

#### Immediate to Accumulator

0010010w	data	data if w = 1
----------	------	---------------

# TEST = AND Function to Flags; No Result

## Register/Memory and Register

1000010w	mod reg r/m

#### Immediate Data and Register/Memory

1111011w	mod 0 0 0 r/m	data	data if w = 1

#### Immediate Data and Accumulator

1010100w	data	data if w = 1

### Or - Or

### Register/Memory and Register to Either

	<del>,</del>
000010dw	mod reg r/m

### Immediate to Register/Memory

Ì	1000000w	mod 0 0 1 r/m	data	data if w = 1	
ı				] wata ii w - i	

#### Immediate to Accumulator

	· · · · · · · · · · · · · · · · · · ·	
0000110	4.4.	
0000110w	data	data if w == 1

### XOR = Exclusive OR

### Register/Memory and Register to Either

001100dw	mod reg r/m
001100uw	mou reg mi

### Immediate to Register/Memory

- 1				
1	1000000w	mod 1 1 0 r/m	data	data if w = 1

## Immediate to Accumulator

0011010w	data	data if w = 1

### NOT = Invert Register/Memory

# **String Manipulation**

MOVS = Move Byte Word

1010010w

CMPS B/W = Compare Byte/Word

1010011w

SCAS = Scan Byte/Word

1010111w

LODS = Load Byte/Word to AL/AX

1010110w

STOS = Store Byte/Word from AL/AX

1010101w

INS = Input Byte/Word from DX Port

0110110w

OUTS = Output Byte/Word to DX Port

0110111w

# REP/REPNE, REPZ/REPNZ = Repeat String

### Repeat Move String

### Repeat Compare String (z/Not z)

1111001z	1010011w

### Repeat Scan String (z/Not z)

1111001z	1010111w

## Repeat Load String

11110011	1010110w

### Repeat Store String

11110011	1010101w
7	10101014

### Repeat Input String

11110011	0110110w
	_

## Repeat Output String

11110011	0110111w

## **Control Transfer**

### CALL = Call

### **Direct within Segment**

11101000	disp-low	disp-high
	disp low	uisp-iiigii

### Register/Memory Indirect within Segment

1111111	1 1	mod 0 1 0 r/m

### Direct Intersegment

10011010   Segment Offset   Segment   Selector	10011010	Segment Offset	Segment Selector
--	----------	----------------	---------------------

### Indirect Intersegment

	The second secon
11111111	mod 0 1 1 r/m (mod ≠ 11)

# JMP = Unconditional Jump

#### Short/Long

11101011	disp-low

### **Direct within Segment**

	<del>,</del>	
11101001	disp-low	disp-high

#### Register/Memory Indirect within Segment

			۱
1111	1111	mod 1 0 0 r/m	ŀ

### **Direct Intersegment**

11101010	Segment Offset	Segment Selector

#### Indirect Intersegment

	T
11111111	mod 1 0 1 r/m (mod ≠ 11)

### RET = Return from Call

#### Within Segment

11000011

#### Within Segment Adding Immediate to SP

	<u> </u>	
11000010	data-low	data-high

### Intersegment

11001011

### Intersegment Adding Immediate to SP

11001010	data-low	data-high

## JE/JZ = Jump on Equal/Zero

01110100	l disn l
01110100	l nigh l

# JL/JNGE = Jump on Less/Not Greater, or Equal

01111100	disp

# JLE/JNG = Jump on Less, or Equal/Not Greater

01111110	disp

# JB/JNAE = Jump on Below/Not Above, or Equal

	r
01110010	disp

JBE/JNA	=	Jump	on	Below.	or	Equal/Not Abov	A

01110110	l diam
1 01110110	disp
	1 .

# JP/JPE = Jump on Parity/Parity Even

01111010	disp

### JO - Jump on Overflow

01110000	disp

### JS = Jump on Sign

01111000	dian
	aisp

## JNE/JNZ = Jump on Not Equal/Not Zero

0111	0101	disp

### JNL/JGE = Jump on Not Less/Greater, or Equal

<del></del>	
01111101	disp
0111101	l dish

# JNLE/JG = Jump on Not Less, or Equal/Greater

01111111	disp
	i aisb

# JNB/JAE = Jump on Not Below/Above, or Equal

01110011	disn
1 01110011	dish

# JNBE/JA = Jump on Not Below, or Equal/Above

	· · · · · · · · · · · · · · · · · · ·
01110111	disp

# JNP/JPO = Jump on Not Parity/Parity Odd

01111011	disp

### JNO = Jump on Not Overflow

01110001	disp

# JNS = Jump on Not Sign

01111001	disp
	4.05

# LOOP = Loop CX Times

disp

# LOOPZ/LOOPE = Loop while Zero/Equal

11100001	disp

# LOOPNZ/LOOPNE = Loop while Not Zero/Not Equal

00000	1100000 disp	
	alop alop	

## JCXZ = Jump on CX Zero

11100011	disp

### **ENTER** = Enter Procedure

11001000	data-low	data-high
	1.	

### **LEAVE** = Leave Procedure

11001001

## INT = Interrupt

**Type Specified** 

11001101

Type 3

11001100

### INTO = Interrupt on Overflow

11001110

## IRET = Interrupt Return

11001111

## **BOUND** = Detect Value Out of Range

01100010 mod reg r/m

#### **Processor Control**

CLC = Clear Carry

11111000

## **CMC** = Complement Carry

11110101

STC = Set Carry

11111001

# CLD = Clear Direction 11111100 STD = Set Direction 11111101 CLi = Clear Interrupt 11111010 STI = Set Interrupt Enable Flag 11111011 HLT = Halt 11110100 WAIT = Wait 10011011 LOCK = Bus Lock Prefix 11110000 CTS = Clear Task Switched Flag 00001111 00000110

mod LLL r/m

11011TTT

#### **Protection Control**

#### LGDT = Load Global Descriptor Table Register

00001111	00000001	mod 0 1 0 r/m
1 0000		

#### SGDT = Store Global Descriptor Table Register

1	00001111	00000001	mod 0 0 0 r/m

#### LIDT = Load Interrupt Descriptor Table Register

ı			
	00001111	00000001	mod 0 1 1 r/m

#### SIDT = Store Interrupt Descriptor Table Register

00001111	00000001	mod 0 0 1 r/m

#### LLDT = Load Local Descriptor Table Register from Register/Memory

	T	
00001111	00000000	mod 0 1 0 r/m

#### SLDT = Store Local Descriptor Table Register from Register/Memory

00001111	00000000	mod 0 0 0 r/m

#### LTR = Load Task Register from Register/Memory

00001111	00000000	mod 0 1 1 r/m

#### STR = Store Task Register to Register/Memory

00001111	0000000	mod 0 0 1 r/m

#### LMSW = Load Machine Status Word from Register/Memory

00001111	00000001	mod 1 1 0 r/m

## SMSW = Store Machine Status Word

00001111	00000001	mod 1 0 0 r/m
		1 1

## LAR = Load Access Rights from Register/Memory

00001111	00000010	mod reg r/m

## LSL = Load Segment Limit from Register/Memory

	00001111	00000011	mod reg r/m
--	----------	----------	-------------

## ARPL = Adjust Requested Privilege Level from Register/Memory

01100011	mod reg r/m

## VERR = Verify Read Access; Register/Memory

00001111	0000000	mod 1 0 0 r/m

## **VERW** = Verify Write Access

00001111	0000000	mod 1 0 1 r/m

The effective address (EA) of the memory operand is computed according to the mod and r/m fields:

If mod = 11, then r/m is treated as a reg field.

If mod = 00, then disp = 0, disp-low and disp-high are absent.

If mod = 01, then disp = disp-low sign-extended to 16 bits,

disp-high is absent.

36

If mod = 10, then disp = disp-high:disp-low.

If r/m = 000, then EA = (BX) + (SI) + DISP

If r/m = 001, then EA = (BX) + (DI) + DISP

If r/m = 010, then EA = (BP) + (SI) + DISP

If r/m = 011, then EA = (BP) + (DI) + DISP

If r/m = 100, then EA = (SI) + DISP

If r/m = 101, then EA = (DI) + DISP

If r/m = 110, then EA = (BP) + DISP

If r/m = 111, then EA = (BX) + DISP

The disp field follows the second byte of the instruction (before data if required).

**Note:** An exception to the above statements occurs when mod = 00and r/m = 110, in which case EA = disp-high; disp-low.

#### **Segment Override Prefix**

The 2-bit and 3-bit reg fields are defined in the following figures.

Reg	Segment Register	Reg	Segment Register	
00	ES	10	SS	
01	cs	11	DS	

Figure 9. 2-Bit Register Field

16-Bit (w = 1)	8-Bit (w = 0)	
000 AX	000 AL	
001 CX	001 CL	
010 DX	010 DL	
011 BX	011 BL	
100 SP	100 AH	
101 BP	101 CH	
110 SI	110 DH	
111 DI	111 BH	

The physical addresses of all operands addressed by the BP register are computed using the SS Segment register. The physical addresses of the destination operands of the string primitive operations (those addressed by the DI register) are computed using the ES segment, which may not be overridden.

## 80287 Math Coprocessor Instruction Set

The following is an instruction-set summary for the 80287 Math Coprocessor.

The following figure shows abbreviations used in the summary.

Field	Description	Bit information
escape	80286 Extension Escape	Bit Pattern = 11011
MF	Memory Format	00 = 32-Bit Real
		01 = 32-Bit Integer
		10 = 64-Bit Real
		11 = 16-Bit Integer
ST(0)	Current Stack Top	
ST(i)	ith Register Below the Stack	
	Тор	
d	Destination	0 = Destination is ST(0)
		1 = Destination is ST(i)
P	Pop	0 = No pop
		1 = Pop ST(0)
R	Reverse*	0 = Destination (op) source
		1 = Source (op) destination
* When d≂	1, reverse the sense of R.	(-)

Figure 11. 80287 Encoding Field Summary

### **Data Transfer**

## FLD = Load

Integer/Real Memory to ST(0)

escape MF 1

Long Integer Memory to ST(0)

escape 1 1 1	mod 1 0 1 r/m

Temporary Real Memory to ST(0)

escape 0 1 1	mod 1 0 1 r/m

#### BCD Memory to ST(0)

	<del></del>
escape 1 1 1	mod 1 0 0 r/m

#### ST(i) to ST(0)

escape 0 0 1	1 1 0 0 0 ST(i)
Occupe o o .	

#### FST = Store

#### ST(0) to Integer/Real Memory

escape MF 1	mod 0 1 0 r/m

#### ST(0) to ST(i)

	<del></del>
escape 1 0 1	1 1 0 1 0 ST(i)

## FSTP = Store and Pop

#### ST(0) to Integer/Real Memory

escape MF 1	mod 0 1 1 r/m
oscape ivii i	11100 0 1 1 1/111

#### ST(0) to Long Integer Memory

escape 1 1 1	mod 1 1 1 r/m

## ST(0) to Temporary Real Memory

escape 0 1 1	mod 1 1 1 r/m

#### ST(0) to BCD Memory

escape 1 1 1	mod 1 1 0 r/m

#### ST(0) to ST(i)

escape 1 0 1	11011ST(i)

## FXCH = Exchange ST(i) and ST(0)

escape 0 0 1	1 1 0 0 1 ST(i)

## Comparison

## FCOM = Compare

## Integer/Real Memory to ST(0)

escape MF 0	mod 0 1 0 r/m

#### ST(i) to ST(0)

escape 0 0 0	1 1 0 1 0 ST(i)

## FCOMP = Compare and Pop

## Integer/Real Memory to ST(0)

escape MF 0	mod 0 1 1 r/m

#### ST(i) to ST(0)

= 1 (1) 10 01 (0)	
escape 0 0 0	1 1 0 1 1 ST(i)

## FCOMPP = Compare ST(1) to ST(0) and Pop Twice

escape 1 1 0	11011001

## FTST = Test ST(0)

escape 0 0 1	11100100

## FXAM = Examine ST(0)

escape 0 0 1	11100101

#### Constants

## FLDZ = Load + 0.0 into ST(0)

escape 0 0 1	11101110
oodapo o o .	

## FLD1 = Load + 1.0 into ST(0)

escape 0 0 1	11101000

## FLDPI = Load $\pi$ into ST(0)

escape 0 0 1	11101011
escape o o i	11101011

## $FLDL2T = Load log_2 10 into ST(0)$

escape 0 0 1	11101001

## FLDL2E = Load $log_2$ e into ST(0)

escape 0 0 1	11101010
Coodpc C C I	11101010

## $FLDLG2 = Load log_{10} 2 into ST(0)$

222222 001	11101100
escape 001	11101100

## FLDLN2 = Load log<sub>e</sub> 2 into ST(0)

escape	001	11101101

#### **Arithmetic**

#### FADD - Addition

#### Integer/Real Memory with ST(0)

escape MF0 mod 0 0 0 r/m		escape MF 0	mod 0 0 0 r/m
--------------------------	--	-------------	---------------

#### ST(i) and ST(0)

escape dP0	1 1 0 0 0 ST(i)
occupo ui o	1 100001(1)

#### **FSUB** = Subtraction

#### Integer/Real Memory with ST(0)

	_·_·
escape MF 0	mod 1 0 R r/m

#### ST(i) and ST(0)

escape dP 0	1110R r/m

#### FMUL = Multiplication

#### Integer/Real Memory with ST(0)

escape MF 0	mod 0 0 1 r/m

#### ST(i) and ST(0)

escape dP 0	11001r/m

#### FDIV = Division

#### Integer/Real Memory with ST(0)

	* *
escape MF 0	mod 11R r/m

#### ST(i) and ST(0)

escape dP 0	1111Rr/m
TOTAL T	

#### FSQRT = Square Root of ST(0)

escape 0 0 1	11111010

## FSCALE - Scale ST(0) by ST(1)

	ا ممدمدمد ا
escape 0 0 1	11111101

## FPREM = Partial Remainder of ST(0) ÷ ST(1)

000000000000000000000000000000000000000	1 4 4 4 4 4 0 0 0
escape 0 0 1	11111000
	1

## FRNDINT = Round ST(0) to Integer

escape 0 0 1	11111100

### FXTRACT = Extract Components of ST(0)

escape 0 0 1	11110100

### FABS = Absolute Value of ST(0)

escape 0 0 1	11100001

#### FCHS = Change Sign of ST(0)

escape 0 0 1	11100000

#### Transcendental

#### FPTAN = Partial Tangent of ST(0)

escape 0 0 1	11110010

## FPATAN = Partial Arctangent of ST(1) ÷ ST(0)

escape 0 0 1	11110011

#### $F2XM1 = 2^{ST(0)} -1$

escape 0 0 1	11110000
1	Į.

## $FYL2X = ST(1) \times Log_2 [ST(0)]$

escape 0 0 1	11110001

## $FYL2XP1 = ST(1) \times Log_2 [ST(0) + 1]$

escape 0 0 1	11111001

#### **Processor Control**

#### FINIT = Initialize NPX

escape 0 1 1	11100011

#### FSETPM = Enter Protected Mode

escape 0 1 1	11100100

#### FSTSW AX = Store Control Word

escape 1 1 1	11100000

#### FLDCW = Load Control Word

escape 0 0 1	mod 1 0 1 r/m

#### FSTCW = Store Control Word

escape 0 0 1	mod 1 1 1 r/m
occupe o o .	

#### FSTSW = Store Status Word

escape 1 0 1	mod 1 1 1 r/m

## FCLEX = Clear Exceptions

escape 0 1 1	11100010

#### **FSTENV** = Store Environment

escape 0 0 1	mod 1 1 0 r/m

#### FLDENV = Load Environment

escape 0 0 1	mod 1 0 0 r/m

#### FSAVE = Save State

escape 1 0 1	mod 1 1 0 r/m

#### FRSTOR = Restore State

escape 1 0 1	mod 1 0 0 r/m
escape I U I	11100 1 0 0 17111

#### FINCSTP = Increment Stack Pointer

escape 0 0 1	11110111

#### FDECSTP = Decrement Stack Pointer

escape 0 0 1	11110110

#### FFREE = Free ST(I)

escape 1 0 1	1 1 0 0 0 ST(i)

#### **FNOP** = No Operation

escape 0 0 1	11010000

## Introduction to the 80386 Instruction Set

The 80386 instruction set is an extended version of the 8086 and 80286 instruction sets. The instruction sets have been extended in two ways:

- The instructions have extensions that allow operations on 32-bit operands, registers, and memory.
- A 32-bit addressing mode allows flexible selection of registers for base and index as well as index scaling capabilities (x2, x4, x8) for computing a 32-bit effective address. The 32-bit effective address yields a 4GB address range.

Note: The effective address size must be less than 64KB in the real-address or virtual-address modes to avoid an exception.

## **Code and Data Segment Descriptors**

Although the 80386 supports all 80286 Code and Data segment descriptors, there are some differences in the format. The 80286 segment descriptors contain a 24-bit base address and a 16-bit limit field, while the 80386 segment descriptors have a 32-bit base address, a 20-bit limit field, a default bit, and a granularity bit.

31	24	23		16	15	08	07	00		0
	Segment Base	e (SB)	Bits	15-0	Segment	Limi	t (SL) Bits 15-0		0	1
	SB Bits 31-24	G D	0 0	SL 19-16	Access Rights	Byte	SB Bits 23	-16	4	8 0 t

Figure 12. 80386 Code and Data Segment Descriptor Format

Note: Bits 31 through 16 shown at offset 4 are set to 0 for all 80286 segment descriptors.

The default (D) bit of the code segment register is used to determine whether the instruction is carried out as a 16-bit or 32-bit instruction. Code segment descriptors are not used in either the real-address mode or the virtual-8086 mode. When the system microprocessor is operating in either of these modes, a D-bit value of 0 is assumed and operations default to a 16-bit length compatible with 8086 and 80286 programs.

The granularity (G) bit is used to determine the granularity of the segment length (1 = page granular, 0 = byte granular). If the value of the 20 segment-limit bits is defined as N, a G-bit value of 1 defines the segment size as follows:

Segment size =  $(N + 1) \times 4KB$ 

4KB represents the size of a page.

#### **Prefixes**

Two prefixes have been added to the instruction set. The Operand Size prefix overrides the default selection of the operand size; the Effective Address Size prefix overrides the effective address size. The presence of either prefix toggles the default setting to its opposite condition. For example:

- If the operand size defaults to 32-bit data operations, the presence of the Operand Size prefix sets it for 16-bit data operations.
- If the effective address size is 16-bits, the presence of the Effective Address Size prefix toggles the instruction to use 32-bit effective address computations.

The prefixes are available in all 80386 modes, including the real-address mode and the virtual-8086 mode. Since the default of these modes is always 16 bits, the prefixes are used to specify 32-bit operations. If needed, either or both of the prefixes may precede any opcode bytes and affect only the instruction they precede.

## **Instruction Format**

The instructions are presented in this format:

Opcode Mode Specifier Address Displacement	Immediate Data
--	----------------

Term	Description	
Opcode	The opcode may be one or two bytes in length. With each byte, smaller encoding fields may be defined.	
Mode Specifier	Consists of the "mod r/m" byte and the "scale-index-base" (s-i-b) byte.	
	The mod r/m byte specifies the address mode to be used. Format: mod T T T $r/m$	
	The "s-i-b" byte is optional and can be used only in 32-bit address modes. It follows the mod r/m byte to fully specify the manner in which the effective address is computed. Format: ss index base	
Address Displacement	Follows the "mod r/m" byte or "s-i-b" byte. It may be 8, 16, or 32 bits.	
Immediate Data	If specified, follows any displacement bytes and becomes the last field of the instruction. It may be 8, 16, or 32 bits.	
	The term "8-bit data" indicates a fixed data length of 8 bits.	
	The term "8-, 16-, or 32-bit data" indicates a variable data length. The length is determined by the w field and the current operand size.	
	If $w = 0$ , the data is always 8 bits.	
	If $w=1$ , the size is determined by the operand size of the instruction.	

Figure 13. Instruction Format

The instructions use a variety of fields to indicate register selection, the addressing mode, and so on. The following figure is a summary of the fields.

Field Name	Field Name Description	
w	Specifies if data is byte or full size. (Full size is either 16 or 32 bits.)	1
d	Specifies the direction of data operation.	1
S	Specifies if an immediate data field must be sign-extended.	1
reg	General address specifier.	3
mod r/m	Address mode specifier (effective address can be a general register).	2 for mod; 3 for r/m
ss	Scale factor for scaled index address mode.	2
index	General register to be used as an index register.	3
base	General register to be used as base register.	3
sreg2	Segment register specifier for CS, SS, DS, and ES.	2
sreg3	Segment register specifier for CS, SS, DS, ES, FS, and GS.	3
tttn	For conditional instructions; specifies a condition asserted or a condition negated.	4

Figure 14. 80386 Instruction Set Encoding Field Summary

## **Encoding**

This section defines the encoding of the fields used in the instruction sets.

#### **Address Mode**

The first addressing byte is the "mod r/m" byte. The effective address (EA) of the memory operand is computed according to the mod and r/m fields. The mod r/m byte can be interpreted as either a 16-bit or 32-bit addressing mode specifier. Interpretation of the byte depends on the address components used to calculate the EA. The following figure defines the encoding of 16-bit and 32-bit addressing modes with the mod r/m byte.

mod r/m	16-Bit Mode	32-Bit Mode (No s-l-b byte)	
00 000	DS:[BX + SI]	DS:[EAX]	
00 001	DS:[BX + DI]	DS:[ECX]	
00 010	SS:[BP + SI]	D\$:[EDX]	
00 011	SS:[BP + DI]	DS:[EBX]	
00 100	DS:[SI]	s-i-b present (see Figure 19 on	
		page 53)	
00 101	DS:[DI]	DS:d32	
00 110	d16	DS:[ESI]	
00 111	DS:[BX]	DS:[EDI]	
01 000	DS:[BX + SI + d8]	DS:[EAX + d8]	
01 001	DS:[BX + DI + d8]	DS:[ECX + d8]	
01 010	SS:[BP + SI + d8]	DS:[EDX + d8]	
01 011	SS:[BP + DI + d8]	DS:[EBX + d8]	
01 100	DS:[SI + d8]	s-i-b present (see Figure 19 on	
		page 53)	
01 101	DS:[DI + d8]	SS:[EBP + d8]	
01 110	SS:[BP + d8]	DS:[ESI + d8]	
01 111	DS:[BX + d8]	DS:[EDI + d8]	
10 000	DS:[BX + SI + d16]	DS:[EAX + d32]	
10 001	DS:[BX + DI + d16]		
10 010	SS:[BP + SI + d16]		
10 011	SS:[BP + DI + d16]	DS:[EBX + d32]	
10 100	DS:[SI + d16]	s-i-b present (see Figure 19 on	
	-	page 53)	
10 101	DS:[DI + d16]	SS:[EBP + d32]	
10 110	SS:[BP + d16]	DS:[ESI + d32]	
10 111	DS:[BX + d16]	DS:[EDI + d32]	

Figure 15. Effective Address (16-Bit and 32-Bit Address Modes)

The displacement follows the second byte of the instruction (before data, if required).

The scale-index-base (s-i-b) byte can be specified as a second byte of addressing information. The s-i-b byte is specified when using a 32-bit addressing mode and the mod r/m byte has the following values:

- r/m = 100
- mod = 00, 01, or 10.

When the s-i-b byte is present, the 32-bit effective address is a function of the mod, ss, index, and base fields. The following figures show the scale factor, Index register selected, and base register selected when the s-i-b byte is present.

88	Scale Factor	
00	1	
01	2	
10	4	
11	8	

Figure 16. Scale Factor (s-i-b Byte Present)

index	Index Register	
000	EAX	
001	ECX	
010	EDX	
011	EBX	
100	No Index Register	The ss field must equal 00 when the index field is 100; if not, the effective address is undefined.
101	EBP	
110	ESI	
111	EDI	

Figure 17. Index Registers (s-i-b Byte Present)

base	<b>Base Register</b>	
000	EAX	
001	ECX	
010	EDX	
011	EBX	
100	ESP	
101	EBP	If mod = 00, then EBP is not used to form the EA; immediate 32-bit address displacement follows the mode specifier byte.
110	ESI	•
111	EDI	

Figure 18. Base Registers (s-i-b Byte Present)

The scaled-index information is determined by multiplying the contents of the Index register by the scale factor. The following example shows the use of the 32-bit addressing mode with scaling where:

- EAX is the base of ARRAY A
- · ECX is the index of the desired element
- · 2 is the scale factor.
  - ; ARRAY\_A is an array of words MOV EAX, offset ARRAY\_A MOV ECX, element\_number MOV BX, [EAX][ECX\*2]

The following figure defines the encoding of the 32-bit addressing mode when the s-i-b byte is present.

**Note:** The mod field is from the mod r/m byte. The base field and scaled-index information are from the s-i-b byte.

Mod Base	32-Bit Address Mode
00 000	DS:[EAX + (scaled index)]
00 001	DS:[ECX + (scaled index)]
00 010	DS:[EDX + (scaled index)]
00 011	DS:[EBX + (scaled index)]
00 100	SS:[ESP + (scaled index)]
00 101	DS:[d32 + (scaled index)]
00 110	DS:[ESI + (scaled index)]
00 111	DS:[EDI + (scaled index)]
01 000	DS:[EAX + (scaled index) + d8]
01 001	DS:[ECX + (scaled index) + d8]
01 010	DS:[EDX + (scaled index) + d8]
01 011	DS:[EBX + (scaled index) + d8]
01 100	SS:[ESP + (scaled index) + d8]
01 101	SS:[EBP + (scaled index) + d8]
01 110	DS:[ESI + (scaled index) + d8]
01 111	DS:[EDI + (scaled index) + d8]
10 000	DS:[EAX + (scaled index) + d32]
10 001	DS:[ECX + (scaled index) + d32]
10 010	DS:[EDX + (scaled index) + d32]
10 011	DS:[EBX + (scaled index) + d32]
10 100	SS:[ESP + (scaled index) + d32]
10 101	SS:[EBP + (scaled index) + d32]
10 110	DS:[ESI + (scaled index) + d32]
10 111	DS:[EDI + (scaled index) + d32]

Figure 19. Effective Address (32-Bit Address Mode — s-i-b Byte Present)

## Operand Length (w) Field

For an instruction performing a data operation, the instruction is executed as either a 32-bit or 16-bit operation. Within the constraints of the operation size, the w field encodes the operand size as either one byte or full operation.

w	16-Bit Data Operation	32-Bit Data Operation	
0	8 Bits	8 Bits	
1	16 Bits	32 Bits	

Figure 20. Operand Length Field Encoding

## Segment Register (sreg) Field

The 2-bit segment register field (sreg2) allows one of the four 80286 segment registers to be specified. The 3-bit segment register (sreg3) allows the 80386 FS and GS segment registers to be specified.

sreg2	sreg3	Segment Register	
00	000	ES	
01	001	CS	
10	010	SS	
11	011	DS	
	100	FS	
	101	GS	
	110	Reserved	
	111	Reserved	

Figure 21. Segment Register Field Encoding

## General Register (reg) Field

The general register is specified by the reg field, which may appear in the primary opcode bytes as the reg field of the mod reg r/m byte, or as the r/m field of the mod reg r/m byte when mod = 11.

reg	16-Bit w/o w	16-Bit w = 0	16-Bit w = 1	32-Bit w/o w	32-Bit w = 0	32-Bit w = 1
000	AX	AL	AX	EAX	AL	EAX
001	CX	CL	CX	ECX	CL	ECX
010	DX	DL	DX	EDX	DL	EDX
011	вх	BL	BX	EBX	BL	EBX
100	SP	AH	SP	ESP	AH	ESP
101	BP	CH	BP	EBP	СН	EBP
110	SI	DH	SI	ESI	DH	ESI
111	DI	вн	DI	EDI	ВН	EDI

Figure 22. General Register Field Encoding

The physical addresses of all operands addressed by the BP register are computed using the SS Segment register. For string primitive operations (those addressed by the DI register), addresses of the destination operands are computed using the ES segment, which may not be overridden.

## **Operation Direction (d) Field**

The operation direction (d) field is used in many two-operand instructions to indicate which operand is the source and which is the destination.

d	Direction of Operation
0	Register/Memory < Register The "reg" field indicates the source operand; "mod r/m" or "mod ss index base" indicates the destination operand.
1	Register< Register/Memory The "reg" field indicates the destination operand; "mod r/m" or "mod ss index base" indicates the source operand.

Figure 23. Operand Direction Field Encoding

## Sign-Extend (s) Field

The sign-extend (s) field appears primarily in instructions having immediate data fields. The s field affects only 8-bit immediate data being placed in a 16-bit or 32-bit destination.

•	8-Bit Immediate Data	16/32-Bit Immediate Data
0	No effect on data	No effect on data
	Sign-extend 8-bit data to fill 16-bit or 32-bit destination	No effect on data

Figure 24. Sign-Extend Field Encoding

## **Conditional Test (tttn) Field**

For conditional instructions (conditional jumps and set-on condition), the conditional test (tttn) field is encoded, with n indicating whether to use the condition (n=0) or its negation (n=1), and ttt defining the condition to test.

tttn	Condition	Mnemonic	
0000	Overflow	0	
0001	No Overflow	NO	
0010	Below/Not Above or Equal	B/NAE	
0011	Not Below/Above or Equal	NB/AE	
0100	Equal/Zero	E/Z	
0101	Not Equal/Not Zero	NE/NZ	
0110	Below or Equal/Not Above	BE/NA	
0111	Not Below or Equal/Above	NBE/A	
1000	Sign	S	
1001	Not Sign	NS	
1010	Parity/Parity Even	P/PE	
1011	Not Parity/Parity Odd	NP/PO	
1100	Less Than/Not Greater or Equal	L/NGE	
1101	Not Less Than/Greater or Equal	NL/GE	
1110	Less Than or Equal/Not Greater Than	LE/NG	
1111	Not Less or Equal/Greater Than	NLE/G	

Figure 25. Conditional Test Field Encoding

## Control, Debug, or Test Register (eee) Field

The following shows the encoding for loading and storing the Control, Debug, and Test registers (eee).

eee Code	Interpreted as Control Register	Interpreted as Debug Register	Interpreted as Test Register
000	CR0	DR0	
001		DR1	
010	CR2	DR2	
011	CR3	DR3	
100			
101			
110		DR6	TR6
111		DR7	TR7

Figure 26. Control, Debug, and Test Register Field Encoding

## **80386 Microprocessor Instruction Set**

#### **Data Transfer**

#### MOV = Move

#### Register to Register/Memory

1000100w	mod reg r/m

#### Register/Memory to Register

1000101w	mod reg r/m

#### Immediate to Register/Memory

1100011w	mod 0 0 0 r/m	8-, 16-, or 32-bit data

#### Immediate to Register (Short Form)

#### Memory to Accumulator (Short Form)

1010000w	full 16- or 32-bit displacement
----------	---------------------------------

#### Accumulator to Memory (Short Form)

1010001w	full 16- or 32-bit displacement

#### Register/Memory to Segment Register

		1		
100011	10	mod	d sreg3 r	/m

#### Segment Register to Register/Memory

10001100	mod sreg3 r/m

## MOVSX = Move with Sign Extension

## Register from Register/Memory

00001111	1011111w	mod reg r/m

## MOVZX = Move with Zero Extension

#### Register from Register/Memory

00001111	1011011w	mod reg r/m

#### PUSH = Push

#### Register/Memory

11111111	mod 1 1 0 r/m

#### Register (Short Form)

01010 reg

## Segment Register (ES, CS, SS, or DS) Short Form

0 0 0 sreg2 1 1 0

#### Segment Register (FS or GS)

00001111	1 0 sreg3 0 0 0

#### **Immediate**

011010s0	0 40 00 1
1 01101080	8-, 16-, or 32-bit data

#### PUSHA - Push All

01100000

#### POP = Pop

#### Register/Memory

10001111	mod 0 0 0 r/m

#### Register (Short Form)

01011 reg

#### Segment Register (ES, SS, or DS) Short Form

0 0 0 sreg2 1 1 1

#### Segment Register (FS or GS)

00001111	1 0 sreg3 0 0 1
----------	-----------------

#### POPA = Pop All

01100001

## XCHG = Exchange

#### Register/Memory with Register

r	
1000011w	mod reg r/m

#### Register with Accumulator (Short Form)

10010 reg

#### IN = Input From:

#### **Fixed Port**

	·
1110010w	port number

#### Variable Port

1110110w

## **OUT = Output To:**

#### Fixed Port

1110011w	port number

#### Variable Port

1110111w

## LEA = Load EA to Register

10001101	mod reg r/m

## **Segment Control**

#### LDS = Load Pointer to DS

11000101	mod reg r/m

#### LES = Load Pointer to ES

	11000100	mod reg r/m
--	----------	-------------

#### LFS = Load Pointer to FS

00001111	10110100	mod reg r/m

## LGS = Load Pointer to GS

00001111	10110101	mod reg r/m

#### LSS = Load Pointer to SS

		<del></del>
00001111	10110010	
1 00001111	10110010	mod reg r/m

## **Flag Control**

CLC = Clear Carry Flag

11111000

CLD = Clear Direction Flag

11111100

CLI = Clear Interrupt Enable Flag

11111010

CLTS = Clear Task Switched Flag

00001111 00000110

**CMC** = Complement Carry Flag

11110101

LAHF = Load AH Into Flag

10011111

POPF = Pop Flags

10011101

PUSHF = Push Flags

10011100

### SAHF = Store AH into Flags

10011110

STC = Set Carry Flag

11111001

STD = Set Direction Flag

11111101

STI = Set interrupt Enable Flag

11111011

#### **Arithmetic**

#### ADD - Add

Register to Register

000000dw mod reg r/m

Register to Memory

0000000 mod reg r/m

Memory to Register

0000001w mod reg r/m

Immediate to Register/Memory

1 0 0 0 0 0 s w mod 0 0 0 r/m 8-, 16-, or 32-bit data

Immediate to Accumulator (Short Form)

0 0 0 0 0 1 0 w 8-, 16-, or 32-bit data

## ADC = Add with Carry

#### Register to Register

-	
000100dw	mod reg r/m
1 0001000 W	IIIOu reg I/III

#### Register to Memory

0001000w	mod reg r/m

## Memory to Register

0001001w	mod reg r/m

#### Immediate to Register/Memory

	<del></del>	
100000sw	mod 0 1 0 r/m	8-, 16-, or 32-bit data

#### Immediate to Accumulator (Short Form)

0 0 0 1 0 1 0 w 8-, 16-, or 32-bit data
---

#### INC = Increment

#### Register/Memory

1111111w	mod 0 0 0 r/m

#### Register (Short Form)

01000 reg

#### SUB = Subtract

#### Register from Register

001010dw	mod reg r/m

## Register from Memory

0010100w	mod reg r/m

#### Memory from Register

0010101w	mod reg r/m

#### Immediate from Register/Memory

100000sw	mod 1 0 1 r/m	8-, 16-, or 32-bit data

## Immediate from Accumulator (Short Form)

ı		
	0010110w	8-, 16-, or 32-bit data

#### SBB = Subtract with Borrow

#### Register from Register

000110dw	mod reg r/m

#### Register from Memory

0001100w	mod reg r/m

#### Memory from Register

0001101w	mod reg r/m

#### Immediate from Register/Memory

100000sw	mod 0 1 1 r/m	8-, 16-, or 32-bit data

## Immediate from Accumulator (Short Form)

0001110w	0 40 . 00 . 11
I UUUIIIUW I	8-, 16-, or 32-bit data
	o, io, or or bit data

#### **DEC** = **Decrement**

#### Register/Memory

1111111w	mod 0 0 1 r/m

#### Register (Short Form)

01001 reg

## CMP = Compare

#### Register with Register

001110dw	mod reg r/m

#### Memory with Register

0011100w	mod reg r/m

#### Register with Memory

0011101w	mod reg r/m
00111011	mod reg i/m

#### Immediate with Register/Memory

- 1			
	100000sw	mod 1 1 1 r/m	8-, 16-, or 32-bit data

#### Immediate with Accumulator (Short Form)

0011110w	8-, 16-, or 32-bit data
0011110#	0-, 10-, 01 02-bit data

## NEG = Change Sign

١		
	1111011w	mod 0 1 1 r/m

## AAA = ASCII Adjust for Add

00110111

#### AAS = ASCII Adjust for Subtract

00111111

#### DAA = Decimal Adjust for Add

00100111

### DAS = Decimal Adjust for Subtract

00101111

## MUL = Multiply (Unsigned)

Accumulator with Register/Memory

1111011w mod 100r/m

## IMUL = Integer Multiply (Signed)

Accumulator with Register/Memory

1111011w mod 101r/m

#### Register with Register/Memory

00001111 10101111 mo	d reg r/m
----------------------	-----------

#### Register/Memory with Immediate to Register

0 1 1 0 1 0 s 1 mod reg r/m 8-, 16-, or 32-bit data	011010s1	mod reg r/m	8-, 16-, or 32-bit data
---	----------	-------------	-------------------------

### DIV = Divide (Unsigned)

#### Accumulator by Register/Memory

1111011w	mod 1 1 0 r/m
IIIIUIIW	mod i romin

#### IDIV = Integer Divide (Signed)

## Accumulator by Register/Memory

1111011w	mod 1 1 1 r/m

## AAD = ASCII Adjust for Divide

11010101	00001010
	00001010

## AAM = ASCII Adjust for Multiply

11010100	00001010

#### **CBW** = Convert Byte to Word

10011000

#### CWD = Convert Word to Doubleword

10011001

## Logic

# Shift/Rotate Instructions Not Through Carry (ROL, ROR, SAL, SAR, SHL, and SHR)

#### Register/Memory by 1

1101000w	mod T T T r/m

#### Register/Memory by CL

1101001w	mod T T T r/m

#### Register/Memory by Immediate Count

1100000w	mod T T T r/m	8-bit data

# Shift/Rotate Instructions Through Carry (RCL and RCR)

#### Register/Memory by 1

1101000w	mod T T T r/m

#### Register/Memory by CL

1101001w	mod TTTr/m

#### Register/Memory by Immediate Count

1 1 0 0 0 0 0 w mod T T T r/m 8-bit data	
--	--

ROL		*			
DOD					
ROR					
RCL					
SHL/SAL					
	RCL RCR SHL/SAL SHR SAR	RCR SHL/SAL SHR	RCR SHL/SAL SHR	RCR SHL/SAL SHR	RCR SHL/SAL SHR

#### SHLD = Shift Left Double

#### Register/Memory by Immediate

00001111	10100100	mod reg r/m	8-bit data

#### Register/Memory by CL

00001111	10100101	mod reg r/m

# SHRD = Shift Right Double

### Register/Memory by Immediate

00001111	10101100	mod reg r/m	8-bit data

### Register/Memory by CL

	<del></del>	
00001111	10101101	mod reg r/m

### AND = And

# Register to Register

001000dw	mod reg r/m

### Register to Memory

0010000w	madragr/m
UUIUUUUW	mod reg r/m

### Memory to Register

0010001w	mod reg r/m

### Immediate to Register/Memory

100000sw	mod 1 0 0 r/m	8-, 16-, or 32-bit data
1000005 W	11100 1 0 0 1/111	0-, 10-, 01 02-bit data

### Immediate to Accumulator (Short Form)

0010010w	8-, 16-, or 32-bit data
0010010#	0,10,0102 511 3414

# TEST - AND Function to Flags; No Result

# Register/Memory and Register

1000010w	mod reg r/m

### Immediate Data and Register/Memory

1111011w	mod 0 0 0 r/m	8-, 16-, or 32-bit data

# Immediate Data and Accumulator (Short Form)

1010100w	0 40 00 5 11 4 - 1
, iololoow	8-, 16-, or 32-bit data

### OR = Or

### Register to Register

_			_
	000010dw	mod reg r/m	

### Register to Memory

0000100w	mod reg r/m

# Memory to Register

0000101w	mod reg r/m

### Immediate to Register/Memory

	· · · · · · · · · · · · · · · · · · ·	
100000sw	mod 0 0 1 r/m	8-, 16-, or 32-bit data

# Immediate to Accumulator (Short Form)

0000110w	8-, 16-, or 32-bit data

### XOR = Exclusive OR

### Register to Register

#### Register to Memory

0011000w	mod reg r/m

#### Memory to Register

0011001w	mod reg r/m
0000	mou rog mm

#### Immediate to Register/Memory

100000sw	mod 1 1 0 r/m	8-, 16-, or 32-bit data

### Immediate to Accumulator (Short Form)

0011010w	8-, 16-, or 32-bit data
1 0011010W	0-, 10-, 01 32-bit data

# NOT = Invert Register/Memory

1111011w	mod 0 1 0 r/m
1	

# **String Manipulation**

# CMPS = Compare Byte Word

1010011w

# INS = Input Byte/Word from DX Port

0110110w

# LODS - Load Byte/Word to AL/AX/EAX

1010110w

MOVS = Move Byte Word

1010010w

OUTS = Output Byte/Word to DX Port

0110111w

SCAS = Scan Byte Word

1010111w

STOS = Store Byte/Word from AL/AX/EX

1010101w

XLAT = Translate String

11010111

# **Repeated String Manipulation**

Repeated by Count in CX or ECX

REPE CMPS = Compare String (Find Non-Match)

11110011 1010011w

# REPNE CMPS = Compare String (Find Match)

44440040	4040044
11110010	1010011w

# **REP INS = Input String**

11110010	0110110w

# REP LODS = Load String

11110010	4040440
11110010	1010110w

# REP MOVS = Move String

11110010	1010010w

# **REP OUTS = Output String**

11110010	0110111w

# REPE SCAS = Scan String (Find Non-AL/AX/EAX)

11110011	1010111w

# REPNE SCAS = Scan String (Find AL/AX/EAX)

11110010	1010111w
11110010	10101111

# **REP STOS** = Store String

11110010	1010101w

# **Bit Manipulation**

# **BSF** = Scan Bit Forward

00001111	10111100	mod reg r/m
----------	----------	-------------

### BSR = Scan Bit Reverse

00001111	10111101	mod reg r/m

### BT = Test Bit

### Register/Memory, Immediate

00001111	10111010	mod 1 0 0 r/m	8-bit data
	L	L	

### Register/Memory, Register

		<u> </u>	
00001	111	10100011	mod reg r/m

# BTC = Test Bit and Complement

#### Register/Memory, Immediate

00001111	10111010	mod 1 1 1 r/m	8-bit data

# Register/Memory, Register

00001111	40444044	· · · · · · · · · · · · · · · · · · ·
00001111	10111011	mod reg r/m

### BTR = Test Bit and Reset

#### Register/Memory, Immediate

-				
	00001111	10111010	mod 1 1 0 r/m	8-bit data

#### Register/Memory, Register

	4		
0000111	1	10110011	mod reg r/m
	•		11100 109 1/11

### BTS = Test Bit and Set

# Register/Memory, Immediate

00001111	10111010	mod 1 0 1 r/m	8-bit data

### Register/Memory, Register

ì			
	00001111	10101011	mod reg r/m

# **Control Transfer**

# CALL - Call

# Direct within Segment

11101000	full 16- or 32-bit displacement

# Register/Memory Indirect within Segment

	·	
111111	11	mod 0 1 0 r/m

### **Direct Intersegment**

10011010	offset, selector
	1

# Indirect Intersegment

0 1 1 r/m

# JMP = Unconditional Jump

### Short

44404044	0.14.41
11101011	8-bit disp.
l .	

#### **Direct within Segment**

1		
	11101001	full 16- or 32-bit displacement

## Register/Memory Indirect within Segment

1111111 mod 100 r/m

### **Direct Intersegment**

11101010	offset, selector

### Indirect Intersegment

11111111	mod 1 0 1 r/m

### RET = Return from Call

### Within Segment

11000011

### Within Segment Adding Immediate to SP

11000010	40 1:4 4:1
11000010	16-bit displacement

#### Intersegment

11001011

#### Intersegment Adding Immediate to SP

11001010	16-bit displacement

# **Conditional Jumps**

# JO = Jump on Overflow

#### 8-Bit Displacement

01110000	8-bit disp.

### **Full Displacement**

00001111	10000000	full 16- or 32-bit displacement

# JNO = Jump on Not Overflow

### 8-Bit Displacement

0.1.1.1.0.0.1	O bit disc.
01110001	8-bit disp.

#### **Full Displacement**

00001111	10000001	full 16- or 32-bit displacement

# JB/JNAE = Jump on Below/Not Above or Equal

### 8-Bit Displacement

01110010	8-bit disp.

### Full Displacement

<del> </del>		
00001111	10000010	full 16- or 32-bit displacement

# JNB/JAE = Jump on Not Below/Above or Equal

### 8-Bit Displacement

01110011	8-bit disp.
	•

### **Full Displacement**

00001111	10000011	full 16- or 32-bit displacement

# JE/JZ = Jump on Equal/Zero

### 8-Bit Displacement

01110100	8-bit disp.
00.00	o bit disp.

### Full Displacement

00001111	10000100	full 16- or 32-bit displacement
		· · · · · · · · · · · · · · · · · · ·

# JNE/JNZ = Jump on Not Equal/Not Zero

## 8-Bit Displacement

01110101 8-bit	disp.
----------------	-------

### **Full Displacement**

00001111	10000101	full 16- or 32-bit displacement

# JBE/JNA - Jump on Below or Equal/Not Above

### 8-Bit Displacement

01110110	8-bit disp.

### **Full Displacement**

-		· · · · · · · · · · · · · · · · · · ·	
1	00001111	10000110	full 16- or 32-bit displacement

# JNBE/JA = Jump on Not Below or Equal/Above

### 8-Bit Displacement

01110111	8-bit disp.

### **Full Displacement**

00001111	10000111	full 16- or 32-bit displacement
00001111	10000111	idii 10- di 32-bit displacement

# JS - Jump on Sign

#### 8-Bit Displacement

01111000	8-bit disp.

# Fuli Displacement

	r	
00001111	10001000	full 16- or 32-bit displacement

# JNS = Jump on Not Sign

# 8-Bit Displacement

01111001	8-bit disp.

#### Full Displacement

· · · · · · · · · · · · · · · · · · ·		
00001111	10001001	full 16- or 32-bit displacement

# JP/JPE = Jump on Parity/Parity Even

### 8-Bit Displacement

01111010	8-bit disp.

### Full Displacement

00001111	10001010	full 16- or 32-bit displacement

# JNP/JPO = Jump on Not Parity/Parity Odd

### 8-Bit Displacement

01111011	8 hit dian
01111011	8-bit disp.

#### Full Displacement

00001111	10001011	full 16- or 32-bit displacement

# JL/JNGE = Jump on Less/Not Greater or Equal

### 8-Bit Displacement

8-bit disp.
o-bit disp.

### Full Displacement

00001111	10001100	full 16- or 32-bit displacement
		idii io oi or or or displacement

# JNL/JGE = Jump on Not Less/Greater or Equal

### 8-Bit Displacement

01111101	8-bit disp.

#### **Full Displacement**

00001111	10001101	full 16- or 32-bit displacement

# JLE/JNG = Jump on Less or Equal/Not Greater

### 8-Bit Displacement

	,
01111110	8-bit disp.
0	o bit disp.

#### Full Displacement

	· · · · · · · · · · · · · · · · · · ·	
00001111	10001110	full 16- or 32-bit displacement

# JNLE/JG = Jump on Not Less or Equal/Greater

### 8-Bit Displacement

01111111	8-bit disp.

# Full Displacement

00001111	10001111	6.11.40 00.614.11.1
1 00001111	1 1 1 1 1 1 1 1 1	full 16- or 32-bit displacement
L		

# JCXZ = Jump on CX Zero

44400044	A L '
1 11100011	8-bit disp.

# JECXZ = Jump on ECX Zero

11100011	8-bit disp.

Note: The operand size prefix differentiates JCXZ from JECXZ.

# LOOP = Loop CX Times

11100010	8-bit disp.
	· · · · · · · · · · · · · · · · · ·

# LOOPZ/LOOPE - Loop with Zero/Equal

11100001	8-bit disp.

# LOOPNZ/LOOPNE = Loop while Not Zero

111100000	0 1 1 1 1
1 11100000	8-bit disp.

# **Conditional Byte Set**

# SETO = Set Byte on Overflow

### To Register/Memory

00001111	10010000	mod 0 0 0 r/m

# SETNO = Set Byte on Not Overflow

#### To Register/Memory

00001111	10010001	mod 0 0 0 r/m
00001111	10010001	moa v v v r/m

# SETB/SETNAE = Set Byte on Below/Not Above or Equal

#### To Register/Memory

00001111	10010010	mod 0 0 0 r/m

# SETNB = Set Byte on Not Below/Above or Equal

### To Register/Memory

00001111	10010011	mod 0 0 0 r/m

# SETE/SETZ = Set Byte on Equal/Zero

#### To Register/Memory

00001111	10010100	mod 0 0 0 r/m

# SETNE/SETNZ = Set Byte on Not Equal/Not Zero

#### To Register/Memory

00001111	10010101	mod 0 0 0 r/m

## SETBE/SETNA = Set Byte on Below or Equal/Not Above

#### To Register/Memory

00001111	10010110	mod 0 0 0 r/m

# SETNBE/SETA = Set Byte on Not Below or Equal/Above

#### To Register/Memory

00001111	10010111	mod 0 0 0 r/m
	10010111	11.00 0 0 17111

## SETS = Set Byte on Sign

### To Register/Memory

00001111	10011000	mod 0 0 0 r/m

### SETNS = Set Byte on Not Sign

#### To Register/Memory

	<del></del>	
00001111	10011001	mod 0 0 0 r/m

# SETP/SETPE = Set Byte on Parity/Parity Even

### To Register/Memory

00001111	10011010	mod 0 0 0 r/m

### SETNP/SETPO = Set Byte on Not Parity/Parity Odd

#### To Register/Memory

		<del></del>
00001111	10011011	mod 0 0 0 r/m

# SETL/SETNGE = Set Byte on Less/Not Greater or Equal

#### To Register/Memory

00001111	10011100	mod 0 0 0 r/m

# SETNL/SETGE - Set Byte on Not Less/Greater or Equal

### To Register/Memory

00001111	01111101	mod 0 0 0 r/m

# SETLE/SETNG - Set Byte on Less or Equal/Not Greater

### To Register/Memory

00001111	10011110	mod 0 0 0 r/m	

# SETNLE/SETG = Set Byte on Not Less or Equal/Greater

### To Register/Memory

00001111	10011111	mod 0 0 0 r/m

#### ENTER = Enter Procedure

11001000	16-bit displacement	8-bit level

### LEAVE = Leave Procedure

11001001

# **Interrupt Instructions**

## INT = Interrupt

#### Type Specified

	·
11001101	type

### Type 3

11001100

# INTO = Interrupt 4 if Overflow Flag Set

11001110

# **BOUND** = Interrupt 5 if Detect Value Out of Range

01100010	mod reg r/m
	_

# IRET = Interrupt Return

11001111

# **Processor Control**

### HLT = Halt

11110100

# MOV - Move to and from Control/Debug/Test Registers

### CR0/CR2/CR3 from Register

00001111	00100010	1 1 eee reg

### Register from CR0-3

00001111	00100000	1 1 eee reg

#### DR0-3, DR6-7 from Register

	-	
00001111	00100011	1 1 eee reg

## Register from DR0-3, DR6-7

00001111	00100001	1 1 eee rea
1 0000	00.000.	, , , , , , , , , , , , , , , , , , ,

# TR6-7 from Register

00001111	00100110	1 1 eee reg
----------	----------	-------------

#### Register from TR6-7

00001111	00100100	1 1 eee reg

# NOP = No Operation

10010000

# WAIT = Wait until BUSY Pin is Negated

10011011

# **Processor Extension**

# **ESC** = Processor Extension Escape

11011TTT	mod L L L r/m

Note: TTT and LLL bits are opcode information for the coprocessor.

# **Prefix Bytes**

#### **Address Size Prefix**

01100111

# **Operand Size Prefix**

01100110

#### LOCK = Bus Lock Prefix

11110000

**Note:** The use of LOCK is restricted to an exchange with memory, or bit test and reset type of instruction.

# **Segment Override Prefix**

CS:

00101110

DS:

00111110

00100110

#### FS:

01100100

#### GS:

01100101

#### SS:

00110110

# **Protection Control**

# ARPL = Adjust Requested Privilege Level from Register/Memory

01100011	mod rog r/m
01100011	mod reg r/m

# LAR = Load Access Rights from Register/Memory

	00001111	00000010	mod reg r/m
--	----------	----------	-------------

# LGDT = Load Global Descriptor Table Register

00001111	00000001	mod 0 1 0 r/m

# LIDT = Load Interrupt Descriptor Table Register

00001111	00000001	mod 0 1 1 r/m

# LLDT = Load Local Descriptor Table Register to Register/Memory

00001111 00000000	mod 0 1 0 r/m
-------------------	---------------

# LMSW = Load Machine Status Word from Register/Memory

00001111	00000001	mod 1 1 0 r/m

# LSL = Load Segment Limit from Register/Memory

00001111	00000011	mod reg r/m

# LTR = Load Task Register from Register/Memory

00001111	0000000	mod 0 0 1 r/m

# SGDT = Store Global Descriptor Table Register

00001111	00000001	mod 0 0 0 r/m

# SIDT = Store Interrupt Descriptor Table Register

	<del></del>	
00001111	00000001	mod 0 0 1 r/m

# SLDT = Store Local Descriptor Table Register to Register/Memory

00001111	0000000	mod 0 0 0 r/m

#### SMSW = Store Machine Status Word

00001111	00000001	mod 1 0 0 r/m

# STR = Store Task Register to Register/Memory

00001111	00000000	mod 0 0 1 r/m

# VERR = Verify Read Access; Register/Memory

00001111	0000000	mod 1 0 0 r/m

# **VERW** = **Verify Write Access**

00001111	00000000	mod 1 0 1 r/m
	1	1

# Introduction to the 80387 Instruction Set

The 80387 instructions use many of the same fields defined earlier in this section for the 80386 instructions. Additional fields used by the 80387 instructions are defined in the following figure.

Field	Description	Bit Information
escape	80386 Extension Escape	Bit Pattern = 11011
MF	Memory Format	00 = 32-bit Real
		01 = 32-bit integer
		10 = 64-bit Real
		11 = 16-bit integer
ST(0)	Current Stack Top	•
ST(i)	ith register below the stack top	
d	Destination	0 = Destination is ST(0)
		1 = Destination is ST(i)
P	Pop	0 = No pop
		1 = Pop ST(0)
R	Reverse*	0 = Destination (op) source
		1 = Source (op) destination
* When d=	1, reverse the sense of R.	(

Figure 27. 80387 Encoding Field Summary

Within the 80387 Instruction Set:

- · Temporary (Extended) Real is 80-bit Real.
- Long Integer is a 64-bit integer.

# 80387 Usage of the Scale-Index-Base Byte

The "mod r/m" byte of an 80387 instruction can be followed by a scale-index-base (s-i-b) byte having the same address mode definition as in the 80386 instruction. The mod field in the 80387 instruction is never equal to 11.

#### Instruction and Data Pointers

The parallel operation of the 80386 and 80387 may allow errors detected by the 80387 to be reported after the 80386 has executed the ESC instruction that caused the error. The 80386/80387 provides two pointer registers to identify the failing numeric instruction. The pointer registers supply the address of the failing numeric instruction and the address of its numeric memory operand when applicable.

Although the pointer registers are located in the 80386, they appear to be located in the 80387 because they are accessed by the ESC instructions FLDENV, FSTENV, FSAVE, and FRSTOR. Whenever the 80386 decodes a new ESC instruction, it saves the address of the instruction along with any prefix bytes that may be present, the address of the operand (if present), and the opcode.

The instruction and data pointers appear in one of four available formats:

- 16-bit Real Mode/Virtual 8086 Mode
- 32-bit Real Mode
- 16-bit Protected Mode
- 32-bit Protected Mode

The Real Mode formats are used whenever the 80386 is in the Real Mode or Virtual 8086 Mode. The Protected Mode formats are used when the 80386 is in the Protected Mode. The Operand Size Prefix can also be used with the 80387 instructions. The operand size of the 80387 instruction determines whether the 16-bit or 32-bit format is used.

Note: FSAVE and FRSTOR have an additional eight fields (10 bytes per field) that contain the current contents of ST(0) through ST(7). These fields follow the instruction and data pointer image shown in the following figures.

The following figures show the instruction and data pointer image format used in the various address modes. The ESC instructions FLDENV, FSTENV, FSAVE, and FRSTOR are used to transfer these values between the 80386/80387 registers and memory.

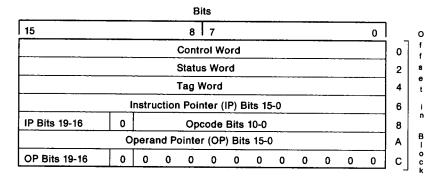


Figure 28. Instruction and Pointer Image (16-Bit Real Address Mode)

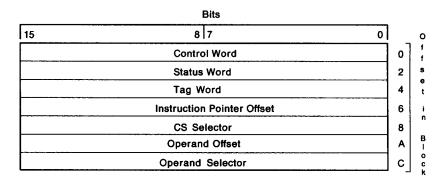


Figure 29. Instruction and Pointer Image (16-Bit Protected Mode)

				Bits	B		
	0	8 7		15	23 16	24	31
0		Control Word				erved	Res
4	Status Word					erved	Res
8	Tag Word					erved	Res
С		IP Bits 15-0			Reserved		
10	-0	Opcode Bits 10-0	0		0 0 0 IP Bits 31-16		0000
14	-0	d Pointer Bits 15-	Opera		Reserved		
18	0000	0000000	0	16	0 0 0 0 Operand Pointer Bits 31-16		

Figure 30. Instruction and Pointer Image (32-Bit Real Address Mode)

			В	its				
31	24	23	16	15	8	7	0	
Re	served				Contro	l Word		0
Re	served			Status Word				4
Re	served		Tag Word				8	
		Inst	ruction I	ointer	Offset			С
Re	served		CS Selector			10		
		Dε	ita Opera	nd Off	set			14
Re	served				Opera	nd Selector		18

Figure 31. Instruction and Pointer Image (32-Bit Protected Mode)

# **New Instructions**

Several new instructions are included in the 80387 instruction set that are not available to the 80287 or 8087 Math Coprocessors. The new instructions are:

FUCOM (Unordered Compare Real)
FUCOMP (Unordered Compare Real and Pop)
FUCOMPP (Unordered Compare Real and Pop Twice)
FPREM1 (IEEE Partial Remainder)
FSINE (Sine)
FCOS (Cosine)
FSINCOS (Sine and Cosine).

# **80387 Math Coprocessor Instruction Set**

The following is an instruction set summary for the 80387 coprocessor. In the following, the bit pattern for escape is 11011.

# **Data Transfer**

#### FLD = Load

#### Integer/Real Memory to ST(0)

escape MF 1	mod 0 0 0 r/m

### Long Integer Memory to ST(0)

escape 1 1 1	mod 1 0 1 r/m

### Temporary Real Memory to ST(0)

escape 0 1 1	mod 1 0 1 r/m

# BCD Memory to ST(0)

escape 1 1 1	mod 1 0 0 r/m

#### ST(i) to ST(0)

esca	pe 0 0 1	1 1 0 0 0 ST(i)

#### FST = Store

#### ST(0) to Integer/Real Memory

escape MF 1	mod 0 1 0 r/m
CSCUPC IVII I	11100 0 1 0 17111

### ST(0) to ST(i)

escape 1 0 1	1 1 0 1 0 ST(i)

### FSTP = Store and Pop

### ST(0) to Integer/Real Memory

escape MF 1 mod 0 1 1 r/m
---------------------------

### ST(0) to Long Integer Memory

escape 1 1 1	mod 1 1 1 r/m

### ST(0) to Temporary Real Memory

escape 0 1 1	mod 1 1 1 r/m

### ST(0) to BCD Memory

es	cape	11	1	mod 1	10 r/m

### ST(0) to ST(i)

31(0) 10 31(1)				
escape 1 0 1	1 1 0 1 1 ST(i)			

# FXCH = Exchange ST(I) and ST(0)

	<del></del>
escape 0 0 1	1 1 0 0 1 ST(i)

# Comparison

# FCOM = Compare

# Integer/Real Memory to ST(0)

escape MF 0	mod 0 1 0 r/m

#### ST(i) to ST(0)

., .,	
escape 0 0 0	1 1 0 1 0 ST(i)

# FCOMP = Compare and Pop

#### Integer/Real Memory to ST(0)

	, ,
escape MF 0	mod 0 1 1 r/m

### ST(i) to ST(0)

escape 0 0 0	11011ST(i)

# FCOMPP = Compare ST(1) to ST(0) and Pop Twice

escape 1 1 0	11011001
oscape i i o	11011001

# FUCOM = Unordered Compare Real

escape 1 0 1	1 1 1 0 0 ST(i)
escape I U I	1110031(1)

# **FUCOMP** = Unordered Compare Real and Pop

escape 1 0 1	11101ST(i)
escape () (	11101ST(i)

# FUCOMPP = Unordered Compare Real and Pop Twice

escape 0 1 0	11101001

# FTST = Test ST(0)

escape 0 0 1	11100100

# FXAM = Examine ST(0)

escape 0 0 1	11100101

### Constants

# FLDZ = Load +0.0 into ST(0)

escape 0 0 1	11101110

## FLD1 = Load +1.0 into ST(0)

escape 0 0 1	11101000

# FLDPI = Load $\pi$ into ST(0)

escape 0 0 1	11101011
000apo 0 0 1	1

# FLDL2T = Load log<sub>2</sub> 10 into ST(0)

escape 0 0 1	11101001

# $FLDL2E = Load log_2 e into ST(0)$

escape 0 0 1	11101010

# $FLDLG2 = Load log_{10} 2 into ST(0)$

escape 0 0 1	11101100

# $FLDLN2 = Load log_e 2 into ST(0)$

escape 0 0 1	11101101

# **Arithmetic**

# FADD = Addition

Integer/Real Memory with ST(0)

escape MF 0	mod 0 0 0 r/m

ST(i) and ST(0)

escape d P 0	1 1 0 0 0 ST(i)

### FSUB = Subtraction

Integer/Real Memory with ST(0)

escape MF 0	mod 1 0 R r/m

ST(i) and ST(0)

escape d P	0 1110Rr/m

# FMUL = Multiplication

Integer/Real Memory with ST(0)

escape MF 0	mod 0 0 1 r/m

ST(i) and ST(0)

escape d P 0	11001r/m

#### FDIV = Division

Integer/Real Memory with ST(0)

escape MF 0	mod 11R r/m

### ST(i) and ST(0)

escape d P 0	1111Rr/m

# FSQRT = Square Root of ST(0)

escape 0 0 1	11111010

# FSCALE = Scale ST(0) by ST(1)

escape 0 0 1	11111101

# FPREM = Partial Remainder of ST(0) ÷ ST(1)

escape 0 0 1	11111000

### FPREM1 = IEEE Partial Remainder

escape 0 0 1	11110101

# FRNDINT = Round ST(0) to Integer

escape 0 0 1	11111100

# **FXTRACT** = Extract Components of ST(0)

	<del>,                                     </del>
escape 0 0 1	11110100

# FABS = Absolute Value of ST(0)

escape 0 0 1	11100001

# FCHS = Change Sign of ST(0)

escape 0 0 1	11100000

# **Transcendental**

# FPTAN = Partial Tangent of ST(0)

escape 0 0 1	11110010

# FPATAN = Partial Arctangent of ST(1) ÷ ST(0)

escape 0 0 1	11110011

### FSIN = Sine

escape 0 0 1	11111110

### FCOS = Cosine

	<del></del>
escape 0 0 1	11111111

### FSINCOS = Sine and Cosine

	T'
escape 0 0 1	11111011

### $F2XM1 = 2^{ST(0)} -1$

escape 0 0 1	11110000

# $FYL2X = ST(1) \times Log_2 [ST(0)]$

escape 0 0 1	11110001

# $FYL2XP1 = ST(1) \times Log_2 [ST(0) + 1]$

escape 0 0 1	11111001

# **Processor Control**

### FINIT = Initialize NPX

	·
escape 0 1 1	11100011

### FSTSW AX = Store Control Word

escape 1 1 1	11100000

### FLDCW = Load Control Word

escape 0 0 1	mod 1 0 1 r/m

#### FSTCW = Store Control Word

escape 0 0 1	mod 1 1 1 r/m

### FSTSW = Store Status Word

escape 1 0 1	mod 1 1 1 r/m

## FCLEX = Clear Exceptions

escape	011	1110	001	0

# **FSTENV** = Store Environment

ŀ			 			
	escap	e 0 0 1	mo	d 1 1	0 r/m	

### FLDENV = Load Environment

escape 0 0 1	mod 1 0 0 r/m

### FSAVE = Save State

	mod 1 1 0 r/m
escape 1 0 1	11100 1 1 0 1/111

### FRSTOR = Restore State

escape 1 0 1	mod 1 0 0 r/m

# FINCSTP = Increment Stack Pointer

escape 0 0 1	11110111

# FDECSTP = Decrement Stack Pointer

escape 0 0 1	11110110
	L

### FFREE = Free ST(I)

escape 1 0 1	1 1 0 0 0 ST(i)

### FNOP = No Operation

	<del>,                                      </del>
escape 0 0 1	11010000

# **80486 Microprocessor Instruction Set**

The 80486 microprocessor uses the same instruction set that the 80386 microprocessor and the 80387 Math Coprocessor. In addition, the 80486 has six unique instructions that control cache operation:

- Byte Swap (BSWAP)
- Compare and Exchange (CMPXCHG)
- Exchange-and-Add (XADD)
- Invalidate Data Cache (INVD)
- Invalidate TLBN Entry (INVLPG)
- Write-Back and Invalidate Data Cache (WBINVD).

# BSWAP = Byte Swap

00001111	11001 reg

# CMPXCHG = Compare and Exchange

#### Register 1, Register 2

00001111	1011000w	11 reg <sup>2</sup> reg <sup>1</sup>

## Memory, Register 2

00001111 1011000w	mod reg <sup>2</sup> mem
-------------------	--------------------------

# XADD = Exchange and Add

### Register 1, Register 2

00001111	1100000w	11 reg <sup>2</sup> reg <sup>1</sup>
1	I	1

### Memory, Register 2

00001111	1100000w	mod reg <sup>2</sup> mem

# INVD = Invalidate Data Cache

00001111	00001000

# WBINVD = Write-Back and Invalidate Data Cache

00001111	00001001

# INVLPG = Invalidate TLB Entry

00001111	00000001	mod 11 mem
	ł .	

# **Notes:**